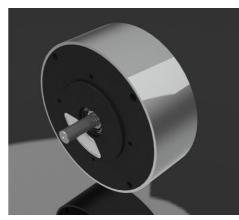
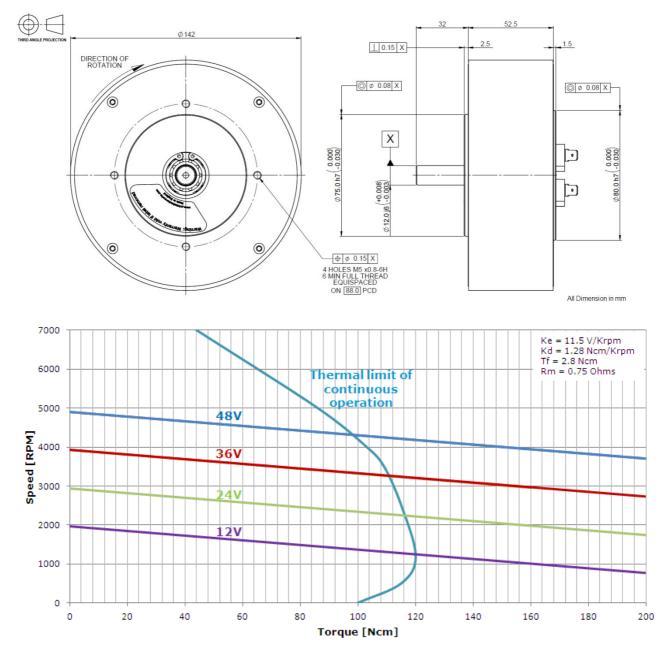




The Printed Motor Works *G*M12 is a precision DC servo motor with high power magnets. The motors are fitted with thermally stable AlNiCo magnets and can be tuned using the charge coils for optimum performance to customer's applications. The GM range is the original pancake motor type and has been successfully used in a variety of applications for decades.





NOTE: The above voltages are examples, not a predefined maximum or minimum. Due to ongoing product improvements data is subject to change without notice.

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GM12



Applications: Servo mechanisms, motion control, industrial robots, CNC machining, printing machinery, logistics solutions, medical mobility, medical scanners, flight simulators, marine autopilots and high ambient temperature ventilation.

Markets: Industrial automation, automotive, medical, life sciences, aerospace, printing, logistics, instrumentation, test and measurement, oil & gas and offshore marine.

Design Modifications

- Encoders
- Timing pulleys
- Long leads
- Tri-rated cable
- US mounting customisation
- Customised shafts
- EMC suppression
 - Connectors
 - Rated for operation in 150°C ambient

| Performance Specifications | Symbol | Units | GM12 |
|---|-----------------|------------------------|----------------|
| Peak Torque | Тр | N/cm (oz/in) | 929 (1316) |
| Rated Speed | Ň | RPM | 3000 |
| Rated Continuous Torque @ 25°C | T ₂₅ | N/cm (oz/in) | 120 (169.9) |
| Rated Power Output | P | Watts | 284 |
| Maximum Recommended Speed | Nmax | RPM | 6000 |
| Continuous Stall Torque | Ts | N/cm (oz/in) | 86 (122) |
| Cogging Torque | Тс | N/cm (oz/in) | 0 (0) |
| Electrical Specifications | | | |
| Rated Terminal Voltage | Е | Volts | 43 |
| Rated Continuous Current | Ī | Amps | 8.8 |
| Peak Current | Ip | Amps | 85 |
| Continuous Stall Current | Is | Amps | 8.0 |
| | 10 | , | 010 |
| Winding Specifications | _ | | |
| Terminal Resistance ± 10% | Rm | Ohms | 0.75 |
| Armature Resistance \pm 10% | Ra | Ohms | 0.61 |
| Back EMF Constant ± 5% | Ke | V/kRPM | 11.5 |
| Torque Constant ± 5% | Kt | N/cm/Amp (oz/in/Amp) | 11.04 (15.63) |
| Viscous Damping Constant | Kd | N/cm/KRPM (oz/in/KRPM) | 1.28 (1.8) |
| Armature Inductance | L | μΗ | <100 |
| Temperature Coefficient of KE | C | %/°C Rise | -0.02 |
| Number of Cummutation Bars | Z | | 141 |
| Mechanical Specifications | | | |
| Moment of Inertia | Jm | kg/cm² (oz/in/sec²) | 1.41 (0.01997) |
| Average Friction Torque | Tf | N/cm (oz/in) | 2.8 (3.97) |
| Weight | W | kg (Ibs) | 3.6 (8.0) |
| Diameter | D | mm (In) | 142 (5.59) |
| Length | LG | mm (In) | 52.5 (2.07) |
| Permitted Radial Load | | Kg (Ibs) | 11.34 (25) |
| Permitted Axial Load | | Kg (Ibs) | 4.99 (11) |
| Figure of Merit | | | |
| Mechanical Time Constant | Tm | ms | 6.68 |
| Electrical Time Constant | Те | ms | < 0.16 |
| | | | |
| Thermal Specifications | | | 1 27 |
| Thermal Resistance at Rated Speed | RAAR | °C/Watt | 1.27 |
| Thermal Resistance at Stall | RAAS | °C/Watt | 1.9 |
| Forced Air Thermal Resistance With 2.0Ibs/min Forced Air | RAA3 | °C/Watt | 0.23 |
| With 2.0105/IIIII Forceu All | KAAS | | 0.25 |

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